

**Amendments to the Claims**

This listing of claims will replace all prior versions, and listing, of claims in the application:

Claim 1 (currently amended) A gyroscope comprising a pair of constituent gyroscopes, each of the constituent gyroscopes comprising:  
a proof mass;  
a frame supporting the proof mass;  
a connection arrangement connecting the proof mass and the frame, the connection arrangement having a first stiffness in a first direction and a second stiffness in [[the]] a second direction substantially perpendicular to the first direction, one of the stiffnesses being significantly greater than the other stiffness; and  
a pair of elements, one of which is a quantum tunnelling sensing tip, adapted to sense motion therebetween in either the first or the second direction.

Claim 2 (original) A gyroscope according to Claim 1, wherein means are provided on each of the constituent gyroscopes to cause the respective proof masses to oscillate in either the first or the second direction, the pairs of elements being adapted to sense motion in the other of the first or the second direction.

Claim 3 (original) A gyroscope according to Claim 1, wherein the means to cause the respective proof masses to oscillate are operable to cause the respective proof masses to oscillate in antiphase with one another.

Claim 4 (previously presented) A gyroscope according to Claim 2, wherein at least one of the means to cause the proof masses to oscillate comprises at least one electrostatic oscillation actuator.

Claim 5 (previously presented) A gyroscope according to Claim 2, wherein at least one of the means to cause the proof masses to oscillate comprises at least one current-carrying element orientated in the other of the first or the second direction, a magnetic field being provided in a direction perpendicular to the first and second directions.

Claim 6 (previously presented) A gyroscope according to Claim 1, wherein at least one of the connection arrangements comprises at least one suspension beam extending between the proof mass and the frame.

Claim 7 (previously presented) A gyroscope according to Claim 1, wherein at least one of the constituent gyroscopes comprises an anchor, the frame of the constituent gyroscope being connected to the anchor.

Claim 8 (original) A gyroscope according to Claim 7, further comprising a positioner located adjacent the frame of the at least one constituent gyroscope, the positioner being connected to the anchor.

Claim 9 (original) A gyroscope according to Claim 8, wherein the positioner is connected to the anchor by at least one spring.

Claim 10 (previously presented) A gyroscope according to Claim 8,

further comprising means to vary the distance between the positioner and the frame.

Claim 11 (original) A gyroscope according to Claim 10, wherein the means to vary the distance between the positioner and the frame comprise at least one electrostatic positioning actuator.

Claim 12 (original) A gyroscope according to Claim 10, wherein the means to vary the distance between the positioner and the frame comprise at least one current-carrying element.

Claim 13 (previously presented) A gyroscope according to Claim 1, wherein one of at least one of the pairs of elements is located on the frame of the respective constituent gyroscope, the other of the at least one of the pairs of elements being located on the proof mass of the respective constituent gyroscope.

Claim 14 (previously presented) A gyroscope according to Claim 8, wherein one of the pair of elements on the at least one constituent gyroscope is located on the positioner, the other of the pair of elements being located on the frame of the at least one constituent gyroscope.

Claim 15 (previously presented) A gyroscope according to Claim 1, wherein at least one of the constituent gyroscopes comprises a further proof mass.

Claim 16 (original) A gyroscope according to Claim 15, wherein the at

least one constituent gyroscope comprising a further proof mass further comprises a strut passing between the proof mass and the further proof mass of the respective constituent gyroscope.

Claim 17 (previously presented) A gyroscope according to Claim 1, wherein the sensed relative motion between each of the pairs of elements is used to maintain a predetermined distance between the elements of each pair of elements.

Claim 18 (previously presented) A gyroscope according to Claim 1, wherein the respective pairs of elements are adapted to sense motion in collinear directions.

Claim 19 (currently amended) A gyroscope comprising:  
a proof mass;  
a frame supporting the proof mass and connected to only one edge thereof by a connection arrangement extending between the proof mass and the frame in a first direction, the connection arrangement having a first stiffness in the first direction and a second stiffness in a second direction substantially perpendicular to the first direction, the first stiffness being significantly greater than the second stiffness;  
a positioner located adjacent the frame; and  
a pair of elements adapted to sense relative motion therebetween in the first direction.

Claim 20 (original) A gyroscope according to Claim 19, further comprising means to cause the proof mass to oscillate in the second

direction.

Claim 21 (original) A gyroscope according to Claim 20, wherein the means to cause the proof masses to oscillate comprise at least one electrostatic oscillation actuator.

Claim 22 (original) A gyroscope according to Claim 20, wherein the means to cause the proof masses to oscillate comprise at least one current carrying element oriented in the first direction.

Claim 23 (previously presented) A gyroscope according to Claim 20, wherein the frame and the proof mass are connected to one another by the connection arrangement such that, during oscillation of the proof mass in the second direction, the proof mass suffers an angular deflection with respect to the frame.

Claim 24 (original) A gyroscope according to Claim 23, wherein the proof mass suffers the angular deflection as a result of a cantilever effect.

Claim 25 (currently amended) ~~A gyroscope according to Claim 19,~~

A gyroscope comprising:

a proof mass;

a frame supporting the proof mass and connected to only one edge thereof by a connection arrangement extending between the proof mass and the frame in a first direction, the connection arrangement having a first stiffness in the first direction and a second stiffness in a second direction substantially perpendicular to the first direction, the first stiffness being

significantly greater than the second stiffness; and  
a pair of elements adapted to sense relative motion therebetween in  
the first direction, wherein one of the pair of elements comprises a quantum  
tunnelling sensing tip, the other of the pair of elements comprising an  
electrode.

Claim 26 (currently amended) A gyroscope according to Claim [[19]]  
25, further comprising a positioner located adjacent the frame.

Claim 27 (original) A gyroscope according to Claim 26, further  
comprising an anchor, the positioner and the frame being connected to the  
anchor.

Claim 28 (original) A gyroscope according to Claim 27, wherein the  
positioner is connected to the anchor by at least one spring.

Claim 29 (previously presented) A gyroscope according to Claim 27,  
wherein means are provided to vary the distance between the positioner and  
the frame.

Claim 30 (original) A gyroscope according to Claim 29, wherein the  
means to vary the distance between the positioner and the frame comprise  
at least one electrostatic positioning actuator.

Claim 31 (original) A gyroscope according to Claim 29, wherein the  
means to vary the distance between the positioner and the frame comprise  
at least one current-carrying element oriented in the second direction, a

magnetic field being provided in a direction perpendicular to the first and second directions.

Claim 32 (previously presented) A gyroscope according to Claim 26, wherein one of the pairs of elements is located on the positioner, the other of the pair of elements being located on the frame.

Claim 33 (previously presented) A gyroscope according to Claim 19, wherein one of the pair of elements is located on the frame, the other of the pair of elements being located on the proof mass.

Claim 34 (original) A gyroscope according to Claim 33, further comprising an anchor, the frame being connected to the anchor.

Claim 35 (original) A gyroscope according to Claim 34, wherein the frame is connected to the anchor at only one end thereof.

Claim 36 (previously presented) A gyroscope according to Claim 29, wherein the one of the pair of elements that is located on the frame is located near the end of the anchor which is not connected to the anchor.

Claim 37 (previously presented) A gyroscope according to Claim 19, wherein the sensed relative motion between the pair of elements is used to maintain a predetermined distance between the pair of elements.

Claim 38 (previously presented) A gyroscope comprising two gyroscopes according to Claim 19, adjacent one another such that the

respective pairs of elements are adapted to sense motion in collinear directions.

Claim 39 (original) A gyroscope according to Claim 38, wherein the collinear directions are opposite collinear directions.

Claims 40-41 (canceled).

Claim 42 (new) A gyroscope according to Claim 25, further comprising means to cause the proof mass to oscillate in the second direction.

Claim 43 (new) A gyroscope according to Claim 42, wherein the means to cause the proof masses to oscillate comprise at least one electrostatic oscillation actuator.